

# TECHNICAL DATASHEET #TDAX020506 QUAD VALVE CONTROLLER with CANopen®

P/N: AX020506

Multiple Digital, Analog, PWM or Pulse Command Inputs 4 Independent Proportional Outputs and 1 On/Off Output 1 CAN Port (CANopen®) 1 - 50 mA. +5V Reference Voltage

#### **Description:**

The quad valve controller provides precise, repeatable control of 4 proportional solenoids and 1 on/off solenoid over a CANopen® network. PWM signal inputs or analog voltage or current inputs are accepted for interface to a PLC, Engine Control Module or command potentiometers. Multiple switched inputs are provided to suit a range of applications. Each can be configured to measure the input value, and send the data to the CAN network. In addition, any output on the controller could be configured to use any of the on board inputs as either a control signal or an enable signal, instead of taking the control information from the CAN bus. Diagnostics messages are provided over the CAN network for the status of inputs or outputs. Using an USB-CAN converter and a PC-based CANopen® configuration tool to access the object dictionary (or a CANopen® master on the network); the operator can configure the controller to suit a wide variety of applications. A convenient feature of the CANopen® Quad is the ability to map any input on the board as the control signal for any output.



#### **Applications:**

The controller is designed for harsh operating environments. Typical applications can include:

- Industrial, off-highway (mobile) and marine applications for control of hydraulic proportional poppet or spool valves
- Interface with a diesel engine's electronic control module PWM signal to drive accessories
- Transmission controls
- Vehicle Traction control

#### Features:

- Independent outputs for 4 proportional solenoids (0....2A) and 1on/off valve (< 5 A)</li>
- Provides a +5V, 50 mA reference voltage to power input devices
- 6 inputs available from the following:
  - Up to 4 voltage or current analog inputs, 0-5V, 0-10V, 4-20 mA or 0-20 mA
  - Up to 6 digital inputs for interface to switches, etc.
  - Up to 2 PWM signal, pulse inputs from sensors or diesel engine ECM's
  - Enable or disable input commands
- Robust 8...36VDC power supply interface with reverse polarity protection
- Thermal overload and overvoltage protection provided
- Rugged IP67 rated packaging with plug-in connections
- Operational from -40 to 85°C (-40 to 185°F)
- CAN (CANopen®) permits networking and provides diagnostics (SAE J1939: model AX020507)
- 1 RS-232 port for diagnostics
- An USB-CAN converter (not supplied) links the PC to the CAN bus for set-up using a commercially-available CANopen® configuration tool (not supplied). Alternatively, the controller can be configured by a CAN master on the network.
- CE type approval for the 2004/104/EC Directive (EMC)

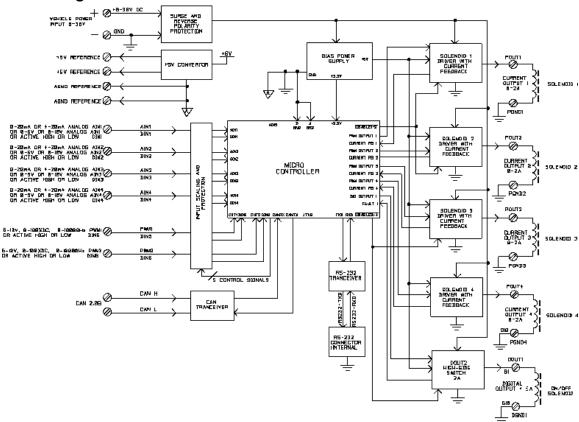
### **Ordering Part Numbers:**

Quad Controller, CANopen®: AX020506

EDS File: EDS-AX020506

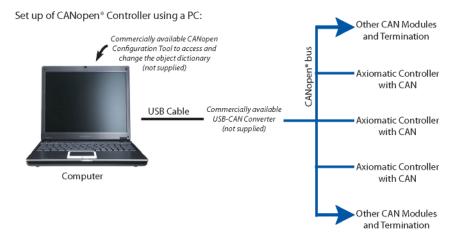
<u>Accessories:</u> **PL-DTM06-12SA-12SB** Mating Plug Kit (no DB-9) (Stock#FG-IOCTRL-19) or **AX070000** Mating Plug Kit with DB-9 or **AX070001** 2-meter wire harness with DB-9

# **Block Diagram:**



Notes: Model shown above depicts full quad hardware capability. RS-232 is available in this model and displaces one of the +5V references.

# Set up of AX020506 Controller using a PC:



# **Technical Specifications:**

Specifications are indicative and subject to change. Actual performance will vary depending on the application and operating conditions. Users should satisfy themselves that the product is suitable for use in the intended application. All our products carry a limited warranty against defects in material and workmanship. Please refer to our Warranty, Application Approvals/Limitations and Return Materials Process as described on <a href="https://www.axiomatic.com/service/">https://www.axiomatic.com/service/</a>.

**Input Specifications** (Refer to the block diagram for an illustration of the input options available.)

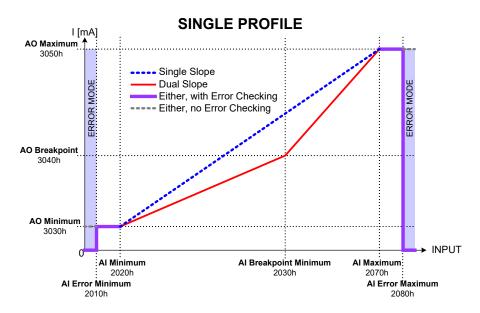
| Power Supply Input -<br>Nominal          | 12 or 24VDC nominal 836 VDC power supply range NB. The maximum total current draw on the power supply pins is 6 Amps @ 24VDC, at one time.   |  |  |
|--|--|--|--|
| Surge and<br>Reverse Polarity Protection | Provided   |  |  |
| All Inputs                               | Up to 6 inputs are selectable by the user and are arranged as 4 analog (named as AIN1AIN4) and 2 frequency (named as FIN1 and FIN2). All inputs, except for frequency and counter, are sampled every 10ms. All inputs operate over the full power supply range of 836VDC. Note the current input is limited to a max. of 10V for continuous operation. |  |  |
|  | With the CANopen® model, AX020506, all input channels are completely independent of each other as well as can simultaneously control an on-board output and send a message to the CANopen® bus. A convenient feature of the CANopen® Quad is the ability to map any input on the board as the control signal for any output.                           |  |  |
|  | To use the CANopen® capabilities, refer to the user manual for details.  |  |  |
| Analog Input Configuration               | Up to 4 analog inputs are available. Refer to Table 1.0. Each analog input can be configured for any one of the following options.  Disable input  05VDC or 010VDC  420mA or 020mA  Digital input (On/Off)   |  |  |
| Frequency Input<br>Configuration         | Up to 2 frequency inputs are available. Refer to Table 1.0.  Each frequency input can be configured for any one of the following options.  • Disable input  • PWM signal  • Pulse (Hz or RPM)  • Digital input (On/Off)  |  |  |
| Analog Ground                            | One analog ground connection is provided.  |  |  |
| Output Reference Voltage                 | 1 +5V, 50 mA NB. Reference voltage is available if digital inputs are active high. Regulation at +/-1% accuracy is provided.   |  |  |
| Input Impedance                          | 10 kOhms for all inputs except 0(4)-20 mA which uses a 249 Ohm current sense resistor  |  |  |

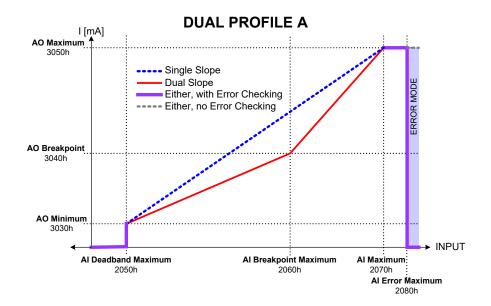
| Input Type              | Description  |  |  |
|-------------------------|--|--|--|
| Disable Inputs          | Each input can be configured as a disable input command. When disable is selected, no CAN messages associated with that channel are sent to the network.   |  |  |
| Universal Analog Inputs | Up to 4 analog inputs are available. Accuracy is +/- 3%. 05VDC or 010VDC 420mA or 020mA  |  |  |
| Digital Inputs          | Up to 6 digital inputs are available. Accuracy is +/- 3%. The input can be configured for either an active high input (switch is connected to a +V signal when ON) or an active low input (switch is connected to a GND signal when ON) and threshold levels are programmable. |  |  |
| PWM Signal Inputs       | Up to 2 PWM inputs are available to interface to a PWM signal from an ECM, PLC or other.  PWM Signal Frequency: 0 – 10,000 Hz  Amplitude: 5-12V  PWM Duty Cycle: 0 to 100%  NB. At ≤1 kHz the input accuracy is +/- 3%. At > 1kHz, it is +/- 5%.(Inputs 5 and 6)               |  |  |
| Pulse Inputs            | Up to 2 pulse inputs are available (Hertz). Accuracy of pulse input (inputs 5,6) is +/- 3%.  |  |  |

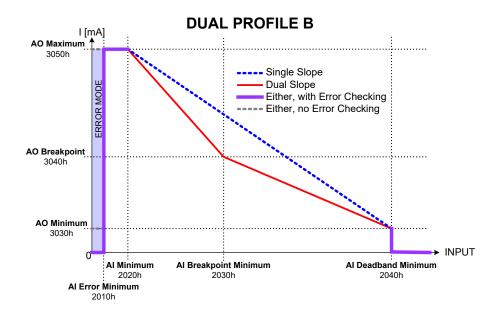
**Output Specifications** 

| High side (sourcing) High frequency PWM The 4 outputs are configurable as proportional or on/off as follows and are named POUT1POUT4. Four independent proportional outputs (02A) NB. The maximum total current draw on the power supply pins is 6 Amps @ 24VDC, at one time.    Table 2.0: Proportional Output Adjustments   | Output Specifications     |  |  |  |  |  |
|---|---------------------------|--|--|--|--|--|
| Adjustable Parameter   Output Current Adjustments   O- Imax (2A) Both minimum and maximum current settings are user configurable.   Superimposed Dither   Dither Adjustments are configurable for each channel. Dither Amplitude: O mA (factory default) Adjustable from 0-400 mA Dither Frequency: 200 Hz (factory default) Adjustments are configurable for each channel. 1,000 mSec (default) Adjustments are configurable for each channel. 1,000 mSec (default) Adjustments are configurable for each channel. 1,000 mSec (default) Adjustments are configurable for each channel. 1,000 mSec (default) Adjustable from 0 to 10,000 mSec (10 sec.).  Proportional Output Logic   The output current is proportional to the control input signal. For the proportional outputs, there are up to six output profiles that can be selected to determine how the output will react to a change at the input. Refer to the graphs below for details. For details on the logic, refer to the user manual.  Digital Output   High side (sourcing) One digital output (≤ 5A) which is named as DOUT.  Digital Output Logic   Refer to the user manual.  Output Accuracy   +/-3%   Protection   Overcurrent protection is provided on both proportional and digital outputs. Short circuit protection is provided on both proportional and digital outputs. | Proportional Outputs      | High frequency PWM The 4 outputs are configurable as proportional or on/off as follows and are named POUT1POUT4. Four independent proportional outputs (02A) NB. The maximum total current draw on the power supply pins is 6 Amps @ 24VDC one time. |  |  |  |  |
| Output Current Adjustments  O- Imax (2A) Both minimum and maximum current settings are user configurable.  Superimposed Dither  Dither adjustments are configurable for each channel. Dither Amplitude: O mA (factory default) Adjustable from 0-400 mA Dither Frequency: 200 Hz (factory default) Adjustable from 50-400 Hz  Ramp Rates Ramp adjustments are configurable for each channel. 1,000 mSec (default) Adjustable from 0 to 10,000 mSec (10 sec.).  Proportional Output Logic  For the proportional outputs, there are up to six output profiles that can be selected to determine how the output will react to a change at the input. Refer to the graphs below for details. For details on the logic, refer to the user manual.  Digital Output  High side (sourcing) One digital output (≤ 5A) which is named as DOUT.  Digital Output Logic  Refer to the user manual.  Output Accuracy  +/-3%  Protection  Overcurrent protection is provided on both proportional and digital outputs. Short circuit protection is provided on both proportional and digital outputs.  |                           |  |  |  |  |  |
| Dither Amplitude: 0 mA (factory default) Adjustable from 0-400 mA Dither Frequency: 200 Hz (factory default) Adjustable from 50-400 Hz  Ramp Rates Ramp adjustments are configurable for each channel. 1,000 mSec (default) Adjustable from 0 to 10,000 mSec (10 sec.).  Proportional Output Logic The output current is proportional to the control input signal. For the proportional outputs, there are up to six output profiles that can be selected to determine how the output will react to a change at the input. Refer to the graphs below for details.  For details on the logic, refer to the user manual.  Digital Output High side (sourcing) One digital output (≤ 5A) which is named as DOUT.  Digital Output Logic  Refer to the user manual.  Output Accuracy +/-3%  Protection Overcurrent protection is provided on both proportional and digital outputs. Short circuit protection is provided on both proportional and digital outputs.   |                           |  | 0- Imax (2A) Both minimum and maximum current settings are   |  |  |  |
| 1,000 mSec (default)   Adjustable from 0 to 10,000 mSec (10 sec.).    Proportional Output Logic   The output current is proportional to the control input signal.   For the proportional outputs, there are up to six output profiles that can be selected to determine how the output will react to a change at the input. Refer to the graphs below for details.   For details on the logic, refer to the user manual.  |                           | Superimposed Dither  | Dither Amplitude: 0 mA (factory default) Adjustable from 0-400 mA Dither Frequency: 200 Hz (factory default) |  |  |  |
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| selected to determine how the output will react to a change at the input. Refer to the graphs below for details.  For details on the logic, refer to the user manual.  Digital Output  High side (sourcing) One digital output (≤ 5A) which is named as DOUT.  Digital Output Logic  Refer to the user manual.  Output Accuracy  +/-3%  Protection  Overcurrent protection is provided on both proportional and digital outputs.  Short circuit protection is provided on both proportional and digital outputs.  | Proportional Output Logic | gic The output current is proportional to the control input signal.  |  |  |  |  |
| Digital Output       High side (sourcing) One digital output (≤ 5A) which is named as DOUT.         Digital Output Logic       Refer to the user manual.         Output Accuracy       +/-3%         Protection       Overcurrent protection is provided on both proportional and digital outputs. Short circuit protection is provided on both proportional and digital outputs.   |                           | selected to determine how the output will react to a change at the input. Refer to the   |  |  |  |  |
| One digital output (≤ 5A) which is named as DOUT.  Digital Output Logic Refer to the user manual.  Output Accuracy +/-3%  Protection Overcurrent protection is provided on both proportional and digital outputs. Short circuit protection is provided on both proportional and digital outputs.  |                           | For details on the logic, refer to the user manual.  |  |  |  |  |
| Output Accuracy +/-3%  Protection Overcurrent protection is provided on both proportional and digital outputs. Short circuit protection is provided on both proportional and digital outputs.   | Digital Output            |  |  |  |  |  |
| Protection Overcurrent protection is provided on both proportional and digital outputs.  Short circuit protection is provided on both proportional and digital outputs.   | Digital Output Logic      | Refer to the user manual.  |  |  |  |  |
| Short circuit protection is provided on both proportional and digital outputs.  | Output Accuracy           | +/-3%  | +/-3%  |  |  |  |
| Error Conditions If an error on the input is detected, the output of the controller shuts off.  | Protection                |  |  |  |  |  |
|   | Error Conditions          | If an error on the input is dete   | If an error on the input is detected, the output of the controller shuts off.                                |  |  |  |

## **Proportional Output Response Profiles:**

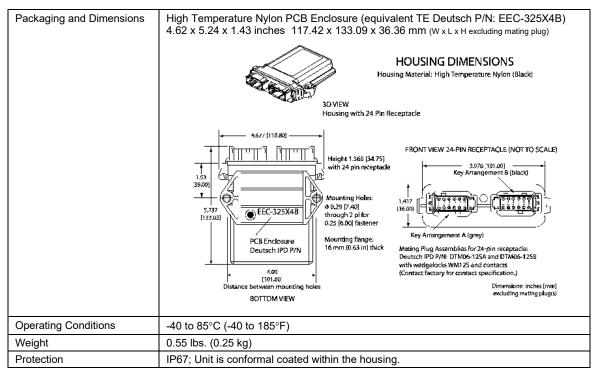






## **General Specifications**

| Microprocessor         | Motorola MC56F8366  |  |  |  |  |
|------------------------|---|--|--|--|--|
| Response Time          | 50 mSec.  |  |  |  |  |
| Control Logic          | Standard embedded software is provided. Refer to the user manual for details. (Application-specific control logic is available on request.)   |  |  |  |  |
| CAN Interface          | 1 CAN port (CANopen®)   |  |  |  |  |
|                        | The controller's object dictionary is compatible with the CiA DS-404 device profile (Device profile for measurement devices and closed-loop controllers). In addition to the standard objects for this device profile, the Quad also includes a number of manufacturer specific objects to extend the functionality beyond that of the basic profile.   |  |  |  |  |
|                        | The Axiomatic Quad, AX020502, is compliant with the following CAN in Automation (CiA) standards.  |  |  |  |  |
|                        | [DS-301] CiA DS-301 V4.02 – CANopen® Application Layer and Communication Profile. CAN in Automation 2002  |  |  |  |  |
|                        | [DS-404] CiA DS-404 V1.2 – Device Profile for Measurement Devices and Closed-Loop Controllers. CAN in Automation 2002   |  |  |  |  |
|                        | [DS-305] CiA DS-305 V2.0 – Layer Setting Service (LSS) and Protocols. CAN in Automation 2006  |  |  |  |  |
| Network Termination    | It is necessary to terminate the network with external termination resistors. The resistors are 120 Ohm, 0.25W minimum, metal film or similar type. They should be placed between CAN_H and CAN_L terminals at both ends of the network.  |  |  |  |  |
| Diagnostics            | Refer to the user manual for details.   |  |  |  |  |
| RS-232 Port            | Available for diagnostic purposes.  |  |  |  |  |
| User Interface         | A CANopen® master on the network or a PC-based CANopen® configuration tool (not supplied) to access the object dictionary and an USB-CAN converter (not supplied) is used for configuration during initial set-up.  |  |  |  |  |
| Approvals              | CE type approval for the 2004/104/EC Directive (EMC)  |  |  |  |  |
| Electrical Connections | Refer to Table 3.0. 24-pin receptacle (equivalent TE Deutsch P/N: DTM13-12PA-12PB-R008) Mating plugs kits are available on request and include: DTM06-12SA and DTM06-12SB with 2 wedgelocks (WM12S) and 24 contacts (0462-201-20141). Plug kit components are TE Deutsch equivalents. 20 AWG wire is recommended for use with contacts 0462-201-20141.  Use dielectric grease on the pins when installing the controller. |  |  |  |  |
|                        | Key Arrangement B (black)   |  |  |  |  |
|                        |   |  |  |  |  |
|                        | Key Arrangement A (grey)  |  |  |  |  |
|                        | FRONT VIEW 24 PIN RECEPTACLE  |  |  |  |  |



#### **Connections**

Table 3.0 - Pin out: AX020506

| Grey<br>Connector<br>PIN # | Function                 | Black<br>Connector<br>PIN # | Function                             |
|----------------------------|--------------------------|-----------------------------|--------------------------------------|
| 12                         | Power -                  | 6                           | Analog In 4 /<br>Digital In 4        |
| 1                          | Power +                  | 7                           | RS-232 Transmit                      |
| 11                         | Proportional Solenoid 1- | 5                           | Analog In 3 /<br>Digital In 3        |
| 2                          | Proportional Solenoid 1+ | 8                           | RS-232 Receive                       |
| 10                         | Proportional Solenoid 2- | 4                           | Analog In 2 / Digital In 2           |
| 3                          | Proportional Solenoid 2+ | 9                           | Analog GND1 (also RS-232 GND)        |
| 9                          | Proportional Solenoid 3- | 3                           | Analog In 1 /<br>Digital In 1        |
| 4                          | Proportional Solenoid 3+ | 10                          | +5V Reference 1                      |
| 8                          | Proportional Solenoid 4- | 2                           | CAN_L                                |
| 5                          | Proportional Solenoid 4+ | 11                          | PWM In 1 / Digital In 5 (See Notes.) |
| 7                          | Digital Solenoid -       | 1                           | CAN_H                                |
| 6                          | Digital Solenoid +       | 12                          | PWM In 2 / Digital In 6 (See Notes.) |

Notes: To ground a PWM input, it is recommended to use the analog GND connection pin.

Active high digital inputs can be connected to the +5V reference.

It is recommended that active low inputs be grounded to the analog GND connection pin.

Note: CANopen® is a registered community trade mark of CAN in Automation e.V.

Form: TDAX020506-06/12/23